

# PROJECT PLANNING SHEET



## Rotary table

<b>Customer Data</b>		
Company:	Industry:	Filled/Confirmed:
Equipment:	Application:	Date:
Quantity:	Budget:	
Prototype:	Serie:	Prototype: Serie:

Rotary Table Installation Type						
<input type="checkbox"/> Horizontal	<input type="checkbox"/> Upside down	<input type="checkbox"/> Vertical	<input type="checkbox"/> Other			

Application Data																				
<table border="1"> <tr><td>Repeatability</td><td>=</td><td>arc-sec</td></tr> <tr><td>Accuracy</td><td>=</td><td>arc-sec</td></tr> <tr><td>Axial run out</td><td>=</td><td>µm</td></tr> <tr><td>Radial run out</td><td>=</td><td>µm</td></tr> </table>	Repeatability	=	arc-sec	Accuracy	=	arc-sec	Axial run out	=	µm	Radial run out	=	µm	<p><b>Extension cable</b> _____ m</p>	<table border="1"> <tr><td>Moment of Inertia<sup>1)</sup></td><td>=</td><td>kgm<sup>2</sup></td></tr> <tr><td>External Moment<sup>2)</sup></td><td>=</td><td>Nm</td></tr> </table>	Moment of Inertia <sup>1)</sup>	=	kgm <sup>2</sup>	External Moment <sup>2)</sup>	=	Nm
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<sup>1)</sup> Describe payload on p. 3 if moment of inertia is not given

<sup>2)</sup> Describe in cycle when applied

Operational Environment Option				
Temperature	Temperature Difference	Clean room	Vacuum	
°C	± °C	Class @ °C ± °C	Pa	

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Special Requirements or Structure	

Free Cycle Description (moving angle, moving time, dwell time)			
e.g.: 100 degree in 0.5 s with 1 s dwell time; 100 degree back in 0.5 s with 100 Nm external moment and 2 s dwell time; ...			
1			
2			
3			
4			
5			
6			
7			
Operation Mode			
torque [M]; operation time [t]; operation with constant torque [dtP]; standstill with unpowered motor [dtR]; standstill with powered motor [dtV]			
<input type="checkbox"/>	S1	M [Nm]	
		t [s]	
<input type="checkbox"/>	S3	M [Nm]	
		dt <sub>P</sub> [s]	
		dt <sub>R</sub> [s]	
<input type="checkbox"/>	S6	M [Nm]	
		dt <sub>P</sub> [s]	
		M dt <sub>V</sub> [Nm]	
		dt <sub>V</sub> [s]	

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Additional features										
Number of cycle/h										
Drive included?	<input type="checkbox"/>	Yes	<input type="checkbox"/>	No						
Existing drive, type										
Existing control system, type										
Required interface										
Required encoder type	<input type="checkbox"/>	Incremental	<input type="checkbox"/>	Absolute						
Required encoder protocol	<input type="checkbox"/>	sin/cos 1 Vpp	<input type="checkbox"/>	TTL	<input type="checkbox"/>	EnDat 2.2	<input type="checkbox"/>	BiSS-C		
Functional Safety encoder required?				<input type="checkbox"/>	Yes	<input type="checkbox"/>	No			
Clamp	<input type="checkbox"/>	None	<input type="checkbox"/>	Power-Off Clamp						
Payload										
Material										
Shape <sup>1)</sup>	<input type="checkbox"/>	Cube	<input type="checkbox"/>	Pyramid	<input type="checkbox"/>	Cone	<input type="checkbox"/>	Cylinder	<input type="checkbox"/>	Other
Number of payload										
Sketch										

<sup>1)</sup> Show in sketch